CANbus • **SAE J1939**

Ranges: 0-90° to 0-50 Turns

Industrial Grade

Specification Summary:

GENERAL

Full Stroke Ranges	0-0.25 to 0-50 turns
Electrical Interface	CANbus SAE J1939
Protocol	Proprietary B
Accuracy	\pm 0.30% full stroke, see ordering information
Repeatability	$\dots \dots \pm 0.02\%$ full stroke
Resolution	± 0.003% full stroke
Enclosure Material	. powder-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Shaft Loading	up to 35 lbs. radial and 5 lbs. axial
Weight, Aluminum (Stainless Steel) En	closure 5 lbs. (10 lbs.), max.

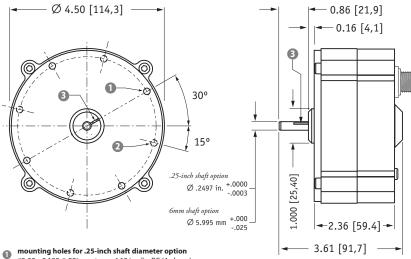
ELECTRICAL

Input Voltage	7 - 18 VDC
Input Current	60 mA max.
Address Setting (Node ID)	063 set via DIP Switches
Baud Rate	125K, 250K or 500K set via DIP Switches
Update Rate	10 ms. (20 ms. available-contact factory)

ENVIRONMENTAL

Environmental Suitability	NEMA 4/4X/6, IP 67/68
Operating Temperature	40° to 185°F
Vibrationug	o to 10 G's to 2000 Hz maximu

Outline Drawing



- #8-32 x 0.180 @ 90° apart on a 4.15 in. dia. BC (4 places)
- mounting holes for 6-mm shaft diameter option M4 x 4.5mm @ 90° apart on a 105.4 mm dia. BC (4 places)
- full counter-clockwise position align mark on shaft to mark on face for start of measurement range

ALL DIMENSIONS ARE IN INCHES [MM]

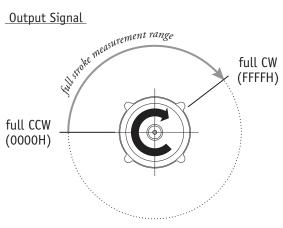
RT9CN



Celesco's model RT9CN communicates rotational position feedback to your PLC via the CANbus SAE J1939 interface. The heart of this sensor is a precision plastic-hybrid position potentiometer which provides a "absolute" position and does not ever have to be reset to a "home" position after a power loss or planned shutdown.

This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/4 to 50 turns.

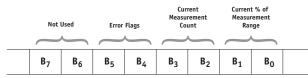
Output Signal



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repetition = 8 msec.

Data Field



 B_0 = LSB current % of measurement range byte B_1 = MSB current % of measurement range byte B_4 - B_5 = error flags

 B_2 = LSB current measurement count byte B_3 = MSB current measurement count byte B_6 - B_7 = not used

Identifier

_	Mess	ssage Priority		riority Future Use		J1939 Re Proprie							Data Field Type*				Not	Used		N	lode 1	D**							
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Hex Value –			()	•		ı	=				F				5	•			3			3	3			ı	=	

*Sensor field data can be factory set to customer specific value.

Setting the Address (Node ID) and Baud Rate

Address Setting (Node ID)

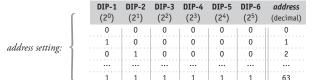
The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number $1 (= 2^0)$ and ending with switch number $6 (= 2^5)$.

Baud Rate

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.



	DIP-7	DIP-8	baud rate
(0	0	125k
ud rate setting: 👌	1	0	250k
	0	1	500k
	1	1	125k



Current % of Measurement Range

The Current % of Measurement Range is a 2-byte value that expresses the current linear position as a percentage of the entire full stroke range. Resolution is .1 % of the full stroke measurement range.

This value starts at **0x0000** at the beginning of the stroke and ends at **0x03E8**.

Example:		D. stored	D
Liample.	Hex	Decimal	Percent
	0000	0000	0.0%
	0001	0001	0.1%
	0002	0002	0.2%
	03F8	1000	100 0%

Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable.

The CMC is a 16-bit value that occupies bytes ${\bf B_0}$ and ${\bf B_1}$ of the data field. ${\bf B_0}$ is the LSB (least significant byte) and ${\bf B_1}$ is the MSB (most significant byte).

The **CMC** starts at **0x0000** with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **0xFFFF**. This holds true for all ranges.

Error Flags

0x55 (yellow LED on controller board) indicates that the sensor has begun to travel beyond the calibrated range of the internal position potentiometer.

OxAA (red LED on controller board) indicates that the sensor has moved well beyond the calibrated range of the internal position potentiometer.

If either error flag occurs within the full stroke range of the sensor, the unit should be returned to the factory for repair and recalibration.

Converting CMC to Degrees

If required, the CMC can easily be converted a rotary measurement expressed in degrees instead of simply counts

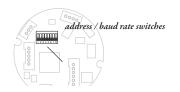
This is accomplished by first dividing the CMC by 65,535 (total counts over the range) and then multiplying that value by the FSR:

Example:

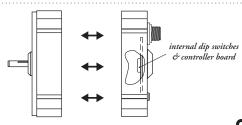
If the full stroke range is 1 turn (360 degrees) and the current position is 0x0FF2 (4082 Decimal) then,

$$\left(\frac{4082}{65,535}\right)$$
 X 360 degrees = 22.4 degrees

CANBus Controller Board and DIP Switch Location



to gain access to the controller board, remove four Allen-Head Screws and separate case halves



^{**}Customer defined, set via Dips 1-6. Bit values shown for example only, see **Address Setting** below.

Model Number:

Sample Model Number:

RT9CN - 30 - AL - 25 - J - 500 - 32 - SC5

R range:
A enclosure:
B shaft:

30 turns powder-painted aluminum .25-in diameter CANbus SAE J1939

interface:
baud rate:

CANbus SAE J19 500 k bits/sec.

inode ID: 3
illustrated states and a second states are second states and a second states are second states and a second states are second

ectrical connection: 5-meter cordset with straight plug

Full Stroke Range:

•										
order code:	R25	R50	1	2	3	5	10	20	30	50
clockwise shaft rotations, min:	0.25	0.50	1	2	3	5	10	20	30	50
accuracy (% of f.s.):	0.3%	0.3%	0.3%	0.3%	0.3%	0.2%	0.15%	0.15%	0.15%	0.15%
potentiometer cycle life*:	2.5 x 10 ⁶	2.5 x 10 ⁶	2.5 x 106	2.5 x 10 ⁶	2.5 x 10 ⁶	5 x 10 ⁵	2.5 x 10 ⁵	2.5 x 10 ⁵	2.5 x 10 ⁵	2.5×10^5

^{*–}number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

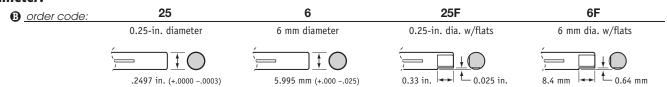
Enclosure Material:

∆ order code: AL SS

powder-painted aluminum

303 stainless steel

Shaft Diameter:



Baud Rate:

① order code: 125 250 500 125 kbaud 250 kbaud 500 kbaud

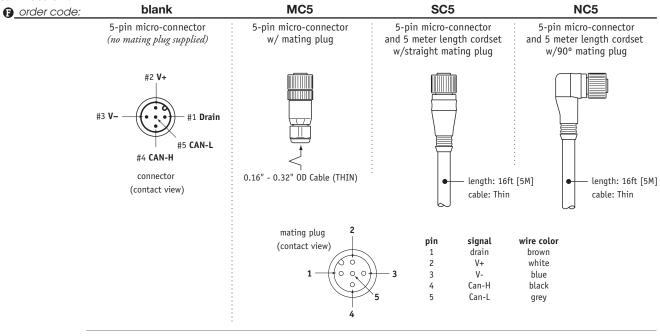
Node ID:

① 1 2 ... 62 63

select address (0 - 63 Decimal)

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Electrical Connection:



DeviceNET®

Ranges: 0-90° to 0-50 Turns

Industrial Grade

Specification Summary:

GENERAL

Full Stroke Ranges	0-0.25 to 0-50 turns
Electrial Interface	CANbus ISO 11898
Protocol	DeviceNet Version 2.0
Accuracy	± 0.30 to 0.15% full stroke
Repeatability	± 0.02% full stroke
Resolution	± 0.003% full stroke
Enclosure Material	. powder-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Shaft Loading	up to 35 lbs. radial and 5 lbs. axial
Weight, Aluminum (Stainless Steel) Er	closure 5 lbs. (10 lbs.), max.

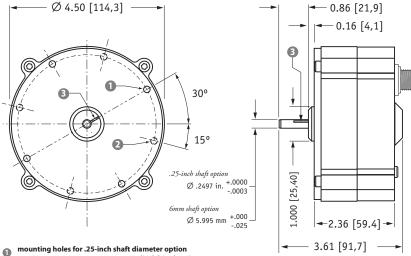
ELECTRICAL

Input Voltage	
Input Current	40 mA
Address Setting (Node ID)	063 set via DIP Switches—default setting: 63
Baud Rate	125K, 250K or 500K set via DIP Switches
EDS file	.available @ http://www.celesco.com/download

ENVIRONMENTAL

Enviromental Suitability	NEMA 4/4X/6, IP67/68
Operating Temperature	40° to 200°F
Vibration up	to 10 G's to 2000 Hz maximum

Outline Drawing



- #8-32 x 0.180 @ 90° apart on a 4.15 in. dia. BC (4 places)
- mounting holes for 6-mm shaft diameter option M4 x 4.5mm @ 90° apart on a 105.4 mm dia. BC (4 places)
- reference mark full counter-clockwise position - align mark on shaft to mark on face for start of measurement range

ALL DIMENSIONS ARE IN INCHES [MM]

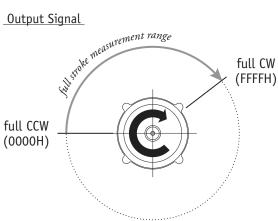
RT9DN



Celesco's model RT9DN communicates rotational position feedback via DeviceNET® to your programmable controller. The heart of this sensor is a precision plastic-hybrid position potentiometer which provides a "absolute" position and does not ever have to be reset to a "home" position after a power loss or planned shutdown.

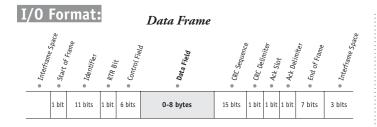
This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/4 to 50 turns.

Output Signal

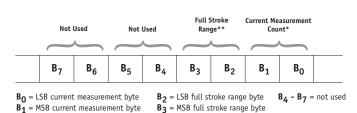


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Celesco Transducer Products, Inc. 20630 Plummer Street • Chatsworth, CA 91311



Data Field



*Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable.

The CMC is a 16-bit value that occupies the first two bytes (B_0 and B_1) of the data field. B_0 is the LSB (least significant byte) and B₁ is the MSB (most significant byte).

The CMC starts at 0000H with shaft at the full counter-clockwise position (0° reference mark) and continues in the clockwise direction to the end of the stroke range stopping at FFFFH. This holds true for all ranges.

**Full Stroke Range

The Full Stroke Range (FSR) is a 16-bit value in the data field that expresses the full range of the sensor in degrees. This value can be used to convert the actual count to units of measurement should the application require it.

The full stroke measurement range occupies the second two bytes (B2 and B3) of the data field.

B₂ is the LSB (least significant byte) and B₃ is the MSB (most significant byte).

This value is expressed in degrees.

Example:

Hex Value	Decimal Equivalent	Full Stroke Range
0168	360	360 degrees

Converting CMC to Degrees

If required, the CMC can easily be converted to a rotational measurement expressed in degrees instead of counts.

This is accomplished by first dividing the CMC by 65,535 (total counts over the range) and then multiplying that value by the FSR:

$$\left(\begin{array}{c} \text{CMC} \\ \hline 65,535 \end{array}\right)$$
 X FSR

Example:

If the full stroke range is 1 turn (360 degrees) and the current position is OFF2 Hex (4082 Decimal)

$$\left(\frac{4082}{65,535}\right)$$
 X 360 deg. = 22.4 degrees

Address Setting (Node ID), Baud Rate and Bus Termination Settings

Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number $1 (= 2^0)$ and ending with switch number $6 (= 2^5)$.

DIP-1 (20)	DIP-2 (2 ¹)	DIP-3 (2 ²)	DIP-4 (2 ³)	DIP-5 (2 ⁴)	DIP-6 (2 ⁵)	address (decimal)					
0	0	0	0	0	0	0					
1	0	0	0	0	0	1					
0	1	0	0	0	0	2					
•••	•••	•••	•••	•••	•••	•••					
1	1	1	1	1	1	63					

Baud Rate

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

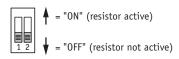
The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

0	125k
0	250k
1	500k
1	125k
	0

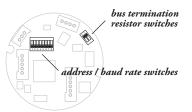
Bus Termination

The setting of the internal bus termination resistor may be specified upon order or manually changed by the end user at the time of installation.

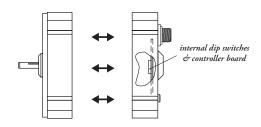
The bus termination resistor is activated setting switches 1 & 2 on the 2-pole DIP switch (located on the internal DeviceNET controller board) to the "ON" position.



DeviceNET Controller Board and DIP Switch Location



to gain access to the controller board, remove four Allen-Head Screws and separate case halves



Model Number:

Sample Model Number:

RT9DN - 30 - AL - 25 - 500 - TR - SC5

30 turns powder-painted aluminum

A enclosure:
B shaft:

.25-in diameter

(baud rate:

500 k bits/sec.

terminating resistor:

 electrical termination: 5-meter cordset with straight plug

Full Stroke Range:

R order code:	R25	R50	1	2	3	5	10	20	30	50
clockwise shaft rotations, min:	0.25	0.50	: 1	. 2	: 3	5	: 10	: 20	: 30	: 50
accuracy (% of f.s.):	0.3%	0.3%	0.3%	0.3%	0.3%	0.2%	0.15%	0.15%	0.15%	0.15%
potentiometer cycle life*:	2.5 x 10 ⁶	5 x 10 ⁵	2.5 x 10 ⁵	2.5 x 10 ⁵	2.5 x 10 ⁵	2.5×10^5				

^{*–}number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

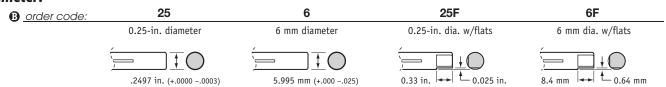
Enclosure Material:

SS A order code:

powder-painted aluminum

303 stainless steel

Shaft Diameter:



Baud Rate:

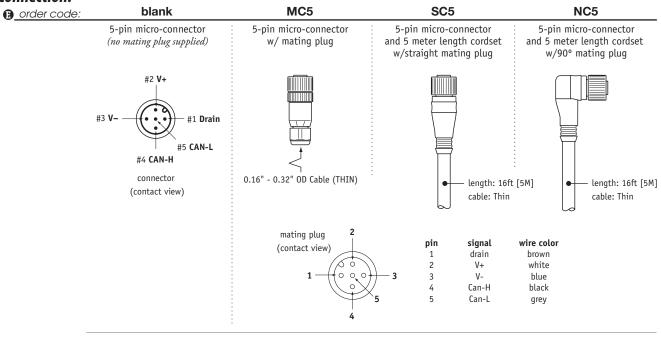
125 250 500 **6** order code: 125 kbaud 250 kbaud 500 kbaud

Terminating Resistor:

n order code: **TR** NR terminating resistor no terminating resistor

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Electrical Connection:



version: 1.0 last updated: April 19, 2005

Precision Potentiometric Output Ranges: 0-90° to 0-50 Turns **Industrial Grade**

RT9101

Specification Summary:

GENERAL

Full Stroke Range Options	0-0.25 to 0-50 turns
Output Signal Options	
Accuracy ± 0.30% to	±0.15% full stroke <i>see ordering information</i>
Repeatability	± 0.02% full stroke
Resolution	essentially infinite
Enclosure Material Options pow	der-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Potentiometer Cycle Life	see ordering information
Shaft Loading	up to 35 lbs. radial and 5 lbs. axial
Weight, Aluminum (Stainless Steel) Enclosu	ure 5 lbs. (10 lbs.) max.

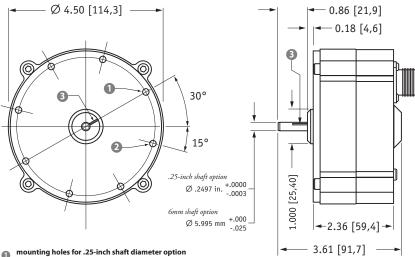
ELECTRICAL

Input Resistance Options500, 1K, 5K, 10K or bridge, see ordering information Output Signal Change Over Full Stroke Range......94% ±4% of input voltage

ENVIRONMENTAL

Enclosure	NEMA 4/4X/6, IP 67/68
Operating Temperature	-40° to 200°F (-40° to 90°C)
Vibrationup to	10 G's to 2000 Hz maximum

Outline Drawing



- #8-32 x 0.180 @ 90° apart on a 4.15 in. dia. BC (4 places)
- mounting holes for 6-mm shaft diameter option M4 x 4,5 mm @ 90° apart on a 105,4 mm dia. BC (4 places)

full counter-clockwise position - align mark on shaft to mark on face for start of measurement range

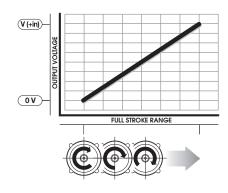
ALL DIMENSIONS ARE IN INCHES [MM]



Celesco's model RT9101 provides a voltage feedback signal for rotational position. The sensing element of this device is a precision plastic-hybrid potentiometer which provied superb linearity and resolution.

This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/4 to 50 turns. Because the sensor is potentiometric, the RT9101 is absolute and will maintain position information even after a loss of power.

Output Signal



celesco

RT9101 • Rotational Transducer: Precision Potentiometric Ouput

Ordering Information:

Model Number:

RT9101-______ - ____ 1_ - ____ 1_ 0 0

Sample Model Number:

RT9101 - 0005 - 111 - 1110

range: 5 turns (clockwise shaft rotations) enclosure: aluminum

B shaft diameter: aluminum .25 inches

output signal: 500 ohm potentiometer electrical connection: 6-pin plastic connector

Full Stroke Range:

J.,										
R order code:	0R25	0R50	0001	0002	0003	0005	0010	0020	0030	0050
clockwise shaft rotations, min:	0.25	0.50	1	2	3	5	10	20	30	50
accuracy (% of f.s.):	0.3%	0.3%	0.3%	0.3%	0.3%	0.2%	0.15%	0.15%	0.15%	0.15%
potentiometer cycle life*:	2.5 x 10 ⁶	5 x 10 ⁵	2.5 x 10 ⁵							

^{*—}number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

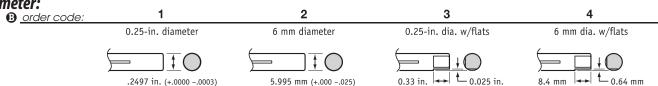
Enclosure Material:

① order code: 1 2

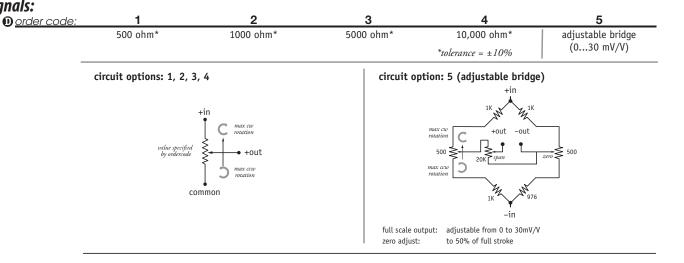
powder-painted aluminum

303 stainless steel

Shaft Diameter:



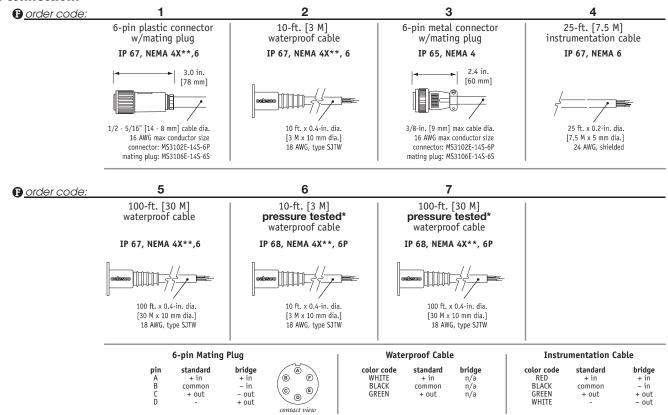
Output Signals:



RT9101 • Rotational Transducer: Precision Potentiometric Ouput

Ordering Information:

Electrical Connection:



*-Test pressure: 100 feet [30 meters] H₂O (40 PSID); Test Medium: Air; Duration: 2 hours. **-Applies to stainless steel enclosure only.

version: 3.0 last updated: June 01, 2011

0/4...20 mA Output • Hazardous Area Certification Ranges: 0-90° to 0-50 Turns

Industrial Grade







RT9420

Specification Summary:

GENERAL	
Full Stroke Range Options	0-0.125 to 0-50 turns
Output Signal Options	420 mA (2-wire) and 020 mA (3-wire)
Accuracy	$\dots \pm 0.30\%$ to $\pm 0.15\%$ full stroke <i>see ordering information</i>
Repeatability	± 0.05% full stroke
	essentially infinite
Enclosure Material Options	powder-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Potentiometer Cycle Life	see ordering information
Shaft Loading	up to 35 lbs. radial and 5 lbs. axial
Weight, Aluminum (Stainless Stee	el) Enclosure 5 lbs. (10 lbs.) max.

ELECTRICAL

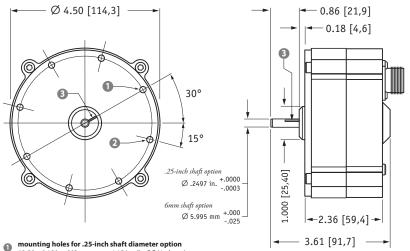
Input Voltage	see ordering information
Input Current	
Maximum Loop Resitance (Load)	(loop supply voltage - 8)/0.020
Circuit Protection	38 mA max.
Impedence	
Output Signal Adjustment	
Zero Adjustment	from factory set zero to 50% of full stroke range
Span Adjustment	to 50% of factory set span
Thermal Effects	,

ENVIRONMENTAL

Enclosure	NEMA 4/4X/6, IP 67/68
Hazardous Area Certification	see ordering information
Operating Temperature	
Vibration	

EMC COMPLIENCE PER DIRECTIVE 89/336/EEC

Emission/Immunity EN50081-2/EN50082-2



- #8-32 x 0.180 @ 90° apart on a 4.15 in. dia. BC (4 places)
- mounting holes for 6-mm shaft diameter option M4 x 4,5 mm @ 90° apart on a 105,4 mm dia. BC (4 places)
- full counter-clockwise position align mark on shaft to mark on face for start of measurement range

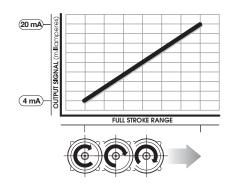
ALL DIMENSIONS ARE IN INCHES [MM]



The RT9420 provides rotational position feedback via 4...20 mA current loop signal. This device combines the superb linearity and resolution of a plastichybrid potentiometer and the durability of Celesco's 4...20mA circuit to provide an accurate and reliable electrical signal. Additionally the zero and span settings are adjustable through access holes in the housing.

This innovative sensor from Celesco, designed to meet NEMA-4 and IP67 standards, is available in full stroke ranges of 1/4 to 50 turns.

Output Signal



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RT9420 • Rotational Transducer: 0/4...20 mA Output

Ordering Information:

Model Number:

Sample Model Number:

RT9420 - 0005 - 111 - 1110

5 turns (clockwise shaft rotations)

aluminum

B shaft diameter:

.25 inches

output signal:

4...20 mA signal increasing clockwise 6-pin plastic connector

Full Stroke Range:

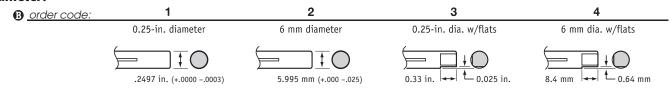
R <u>order code:</u>	R125	0R25	0R50	0001	0002	0003	0005	0010	0020	0030	0050
clockwise shaft rotations, min:	0.125	0.25	0.50	1	2	3	5	10	20	30	50
accuracy (% of f.s.):	0.3%	0.3%	0.3%	0.3%	0.3%	0.3%	0.2%	0.15%	0.15%	0.15%	0.15%
potentiometer cycle life*:	2.5 x 10 ⁶	5 x 10 ⁵	2.5 x 10 ⁵								

^{*–}number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

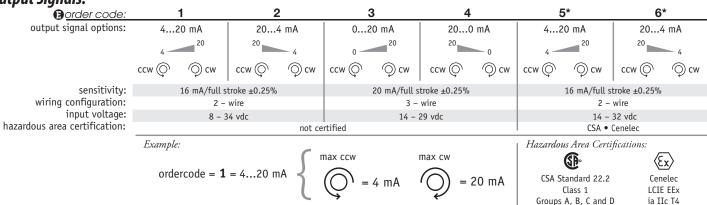
Enclosure Material:

A order code: powder-painted aluminum 303 stainless steel

Shaft Diameter:



Output Signals:

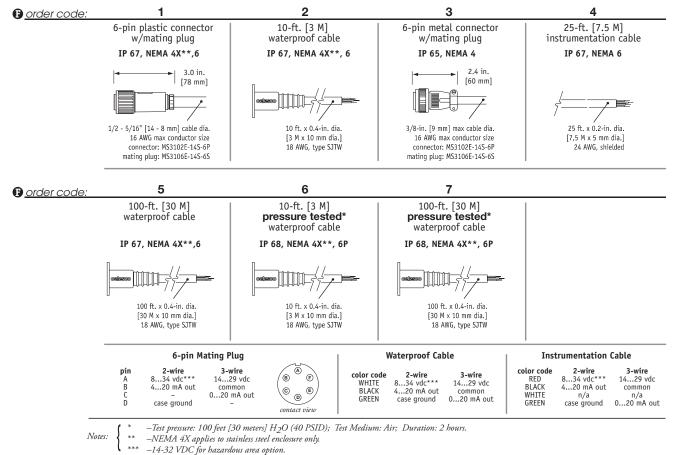


*IMPORTANT: intrinsically safe when powered from a CSA certified zener barrier rated 28 VDC max, 110 mA max per installation drawing#677984

RT9420 • Rotational Transducer: 0/4...20 mA Output

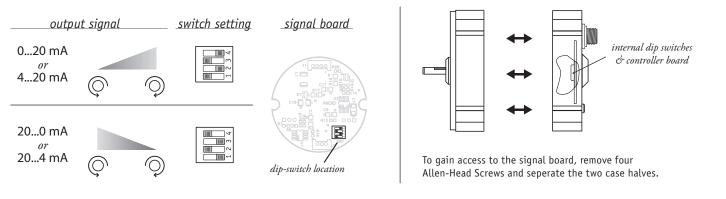
Ordering Information:

Electrical Connection:



Output Signal Selection:

The output signal direction can be reversed at any time by simply changing the dip-switch settings found on the internal signal board. After the settings have been changed, adjustment of the Zero and Span trimpots will be required to precisely match signal values to the beginning and end points of the stroke.



version: 6.0 last updated: May 21, 2013



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0...5, 0...10 VDC Output

Ranges: 0-90° to 0-50 Turns

Industrial Grade

RT9510

Specification Summary:

GENERAL

Full Stroke Range Options	0-0.125 to 0-50 turns
Output Signal Options	05, 010 VDC
Accuracy	±0.15% full stroke <i>see ordering information</i>
Repeatability	± 0.05% full stroke
Resolution	essentially infinite
Enclosure Materialpow	vder-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Potentiometer Cycle Life	see ordering information
Shaft Loading	up to 35 lbs. radial and 5 lbs. axial
Weight, Aluminum (Stainless Steel) Enclosu	ure 5 lbs. (10 lbs.) max.

ELECTRICAL

Input	14.5-40 VDC (10.5-40 VDC for 05 volt output)
	10 mA maximum
Output Impedence	1000 ohms
	5000 ohms
Zero Adjustment	. from factory set zero to 50% of full stroke range
	to 50% of factory set span

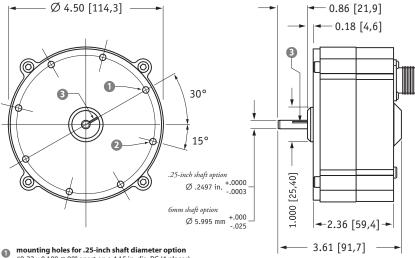
ENVIRONMENTAL

Enclosure	NEMA 4/4X/6, IP 67/68
Operating Temperature	40° to 200°F (-40° to 90°C)
Vibration	up to 10 G's to 2000 Hz maximum

EMC COMPLIENCE PER DIRECTIVE 89/336/EEC

Emission/Immunity......EN50081-2 / EN50082-2

Outline Drawing



- #8-32 x 0.180 @ 90° apart on a 4.15 in. dia. BC (4 places)
- mounting holes for 6-mm shaft diameter option M4 x 4,5 mm @ 90° apart on a 105,4 mm dia. BC (4 places)

full counter-clockwise position - align mark on shaft to mark on face for start of measurement range

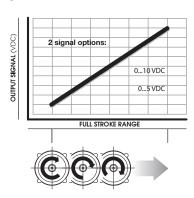
ALL DIMENSIONS ARE IN INCHES [MM]



The RT9510 is an incredibly simple device which provides a regulated 0...10 VDC rotational-position feedback signal with a 14.5...40 VDC unregulated input voltage.

This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/4 to 50 turns. Because the sensor is potentiometric, the RT9510 is absolute and will maintain position information even after a loss of power.

Output Signal



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RT9510 • Rotational Transducer: 0...5, 0...10 VDC Output

Ordering Information:

Model Number:

RT9510-______ -____ 1_ - 1_ 0 - 1_ 0 - 0

Sample Model Number:

RT9510 - 0005 - 111 - 1110

5 turns (clockwise shaft rotations) A enclosure:
B shaft diameter:
c output signal:
electrical connection: aluminum

.25 inches
0...10 VDC signal increasing clockwise 6-pin plastic connector

Full Stroke Range:

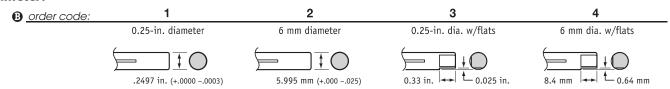
R order code:	R125	0R25	0R50	0001	0002	0003	0005	0010	0020	0030	0050
clockwise shaft rotations, min:	0.125	0.25	0.50	1	2	3	5	10	20	30	50
accuracy (% of f.s.):	0.3%	0.3%	0.3%	0.3%	0.3%	0.3%	0.2%	0.15%	0.15%	0.15%	0.15%
potentiometer cycle life*:	2.5×10^6	2.5 x 10 ⁶	5 x 10 ⁵	2.5 x 10 ⁵							

^{*–}number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

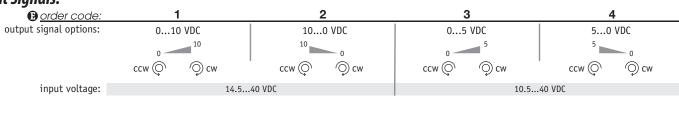
Enclosure Material:

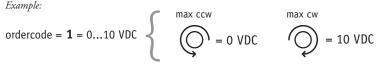
A order code: powder-painted aluminum 303 stainless steel

Shaft Diameter:



Output Signals:

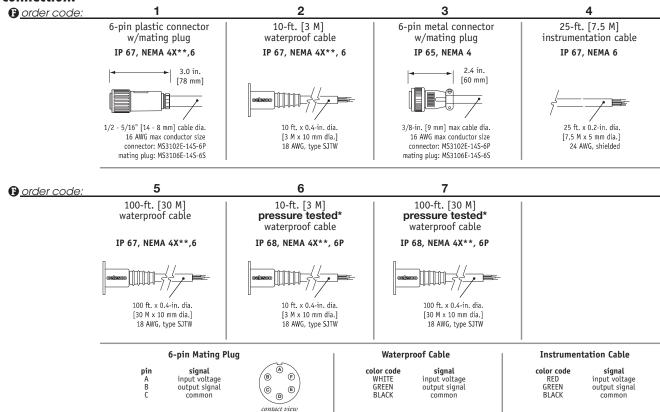




RT9510 • Rotational Transducer: 0...5, 0...10 VDC Output

Ordering Information:

Electrical Connection:



^{*–}Test pressure: 100 feet [30 meters] H₂O (40 PSID); Test Medium: Air; Duration: 2 hours. **–Applies to stainless steel enclosure only.

Output Signal Selection:

The output signal direction can be reversed at any time by simply changing the dip-switch settings found on the internal signal board. After the settings have been changed, adjustment of the Zero and Span trimpots will be required to precisely match signal values to the beginning and end points of the stroke.

